Modeling Correlated Defaults: First Passage Model under Stochastic Volatility

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Abstract

Default dependency structure is crucial in pricing multi-name credit derivatives as well as in credit risk management. In this paper, we extend the first passage model for one name with stochastic volatility (Fouque-Sircar-Sølna, Applied Mathematical Finance 2006) to the multi-name case. Correlation of defaults is generated by correlation between the Brownian motions driving the individual names as well as through common stochastic volatility factors. A numerical example for the loss distribution of a portfolio of defaultable bonds is examined after stochastic volatility is incorporated.

1 Introduction

Default dependency structure is a crucial issue in pricing multi-name credit derivatives as well as in credit risk management. For a multi-name credit derivative, the default dependency structure among the underlying portfolio of reference entities is as important as, and in many cases even more important than, the individual term structures of default probabilities.

On the other hand, it is well documented in the finance literature that stock returns exhibit stochastic volatility. It has been shown in Fouque, Papanicolaou and Sircar (2000) that asymptotic methods are very efficient in capturing the effects of stochastic volatility in simple robust corrections to the constant volatility formulas. Recently, by incorporating stochastic volatility to the first passage model developed by Black and Cox (1976) in modeling defaultable bonds, Fouque, Sircar and Sølna (2006) obtained much higher yield spreads for short maturity bonds than those under

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constant volatility. In fact those low yield spreads at short maturities is exactly what the original first passage model — in fact all firm’s value models — have been criticized for. By using models incorporating fast and slow stochastic volatility factors, and a combination of singular and regular perturbations techniques they obtain reasonable fits to defaultable bonds data.

In this paper, we extend the first passage model to model default dependency in two directions: by extending to multi-dimension and by incorporating stochastic volatility. We derive approximations for the joint survival probabilities and subsequently for the distribution of number of defaults in a basket of names. Since we are not considering in this paper particular structured products such as CDOs, we do not specify all the features of the defaultable bonds except that an individual bond defaults at the first time that the underlying firm’s value goes to or below some exogenously prespecified level — the default threshold. Also, for simplicity, we assume zero recovery for each bond considered. The remark in Fouque et al. (2006) (Section 2) on how to incorporate recovery by considering more general boundary value conditions applies to the present work as well.

The rest of this paper is organized as follows. We first set up in Section 2 the class of models that we consider. We study first the case where the Brownian motions driving the names are independent so that the correlation of defaults is only due to the common factors of stochastic volatility. Then in Section 3, using combined regular and singular perturbation techniques, as in Fouque et al. (2003) for a single name, we obtain approximations for the joint survival probabilities. Specifically, we give a formula for the leading order term and we characterize the corrections terms as solutions of partial differential equations. The derivation of these equations is presented in Appendix A and explicit formulas are given in Appendix B. In Section 4, we examine the loss distribution for a portfolio of defaultable bonds. The general case is examined briefly, and then a special case — homogeneous portfolio case — is examined in detail. Following this, some numerical results illustrating the effect of stochastic volatility are presented for the homogeneous portfolio case. Finally in Section 5 we generalize our model to the case where the Brownian motions driving the names are correlated. We show that an expansion around the independent case can be performed and gives a tractable way to combine this source of default correlation with the one coming from stochastic volatility. Our result shows that for a given maturity the dependency generated by correlating the Brownian motions driving the names is of the same nature as the one generated by stochastic volatility. However they differ across maturities and therefore we conclude that both sources of default correlation should be taken into account when pricing CDO’s tranches for instance.

2 Model Setup

We consider a pool of $n$ defaultable bonds whose underlying firms’ value processes $\{X_t^{(i)}\}_{i=1}^n$ exhibit the following multi-factor stochastic volatility dynamics under the physical probability measure $\mathbb{P}$ — the real world probability measure:

$$
\begin{align*}
\mathrm{d}X_t^{(1)} & = \mu_1 X_t^{(1)} \mathrm{d}t + f_1(Y_t, Z_t) X_t^{(1)} \mathrm{d}W_t^{(1)}, \\
\mathrm{d}X_t^{(2)} & = \mu_2 X_t^{(2)} \mathrm{d}t + f_2(Y_t, Z_t) X_t^{(2)} \mathrm{d}W_t^{(2)}, \\
& \quad \ldots \quad \ldots \quad \ldots \quad \ldots \\
\mathrm{d}X_t^{(n)} & = \mu_n X_t^{(n)} \mathrm{d}t + f_n(Y_t, Z_t) X_t^{(n)} \mathrm{d}W_t^{(n)},
\end{align*}
$$
where \( W_t^{(i)} \)'s are standard Brownian motions and we consider first the uncorrelated case corresponding to \( d\langle W^{(i)}, W^{(j)} \rangle_t = 0 \) for \( i \neq j \). The stochastic volatility correlation structure is given by:

\[
d\langle W^{(Y)}, W^{(i)} \rangle_t = \rho_{YY} dt, \quad d\langle W^{(Z)}, W^{(i)} \rangle_t = \rho_{ZZ} dt, \quad d\langle W^{(Y)}, W^{(Z)} \rangle_t = \rho_{YZ} dt,
\]

with all \( \rho \)'s being constant numbers between \(-1\) and \(1\). Note that \( \sum_{i=1}^{n} \rho_{Yi}^2 \leq 1 \) and \( \sum_{i=1}^{n} \rho_{Zi}^2 \leq 1 \) must be satisfied if the Brownian motions \( W_t^{(i)} \)'s are to be independent. Also \( \mu_i, \epsilon, \delta, m_Y, \nu_Y, m_Z, \nu_Z \) are all constant numbers with \( \epsilon > 0 \) and \( \delta > 0 \) both being small so that stochastic volatilities are driven by two Ornstein-Uhlenbeck (OU) processes, \( Y_t \) being fast mean-reverting with rate of mean-reversion \( 1/\epsilon \) and the invariant distribution \( \mathcal{N}(m_Y, \nu_Y^2) \), and \( Z_t \) being slowly mean-reverting with rate of mean-reversion \( \delta \) and the invariant distribution \( \mathcal{N}(m_Z, \nu_Z^2) \). The function \( f_i \)'s are positive functions, smooth with respect to the slow variable \( z \), and are assumed here, for instance, to be bounded above and below away from zero.

**Remark.** We start by assuming independence among the Brownian motions \( W_t^{(i)} \)'s for \( i = 1, 2, \ldots, n \) basically for two reasons. Firstly, we try to avoid the intractability caused by the interdependence, as can be seen in Zhou (2001) where results on the joint distribution of two hitting times are derived. This dependency will be restored in Section 5 and made tractable by using a perturbation argument around the uncorrelated case. Secondly, we argue that the dependence among the defaultable names introduced through stochastic volatilities is as important as the dependence generated by the interdependence among the Brownian motions driving them. This important issue will be discussed further in Section 5.

Under the risk-neutral probability measure \( \tilde{\mathbb{P}} \), chosen by the market through derivatives trading, the dynamics becomes

\[
\begin{align*}
dX_t^{(1)} &= rX_t^{(1)} dt + f_1(Y_t, Z_t) X_t^{(1)} d\tilde{W}_t^{(1)}, \\
dX_t^{(2)} &= rX_t^{(2)} dt + f_2(Y_t, Z_t) X_t^{(2)} d\tilde{W}_t^{(2)}, \\
&\vdots \\
dX_t^{(n)} &= rX_t^{(n)} dt + f_n(Y_t, Z_t) X_t^{(n)} d\tilde{W}_t^{(n)}, \\
dY_t &= \left[ \frac{1}{\epsilon}(m_Y - Y_t) - \frac{\nu_Y \sqrt{2}}{\sqrt{\epsilon}} \Lambda_1(Y_t, Z_t) \right] dt + \frac{\nu_Y \sqrt{2}}{\sqrt{\epsilon}} d\tilde{W}_t^{(Y)}, \\
dZ_t &= \left[ \delta(m_Z - Z_t) - \nu_Z \sqrt{2\delta} \Lambda_2(Y_t, Z_t) \right] dt + \nu_Z \sqrt{2\delta} d\tilde{W}_t^{(Z)},
\end{align*}
\]

where \( r \) is the riskfree interest rate (assumed constant here), \( \tilde{W}_t^{(i)} \)'s are standard Brownian motions with \( d\langle \tilde{W}^{(i)}, \tilde{W}^{(j)} \rangle_t = 0 \) for \( i \neq j \), and

\[
\begin{align*}
d\langle \tilde{W}^{(Y)}, \tilde{W}^{(i)} \rangle_t &= \rho_{YY} dt, \\
d\langle \tilde{W}^{(Z)}, \tilde{W}^{(i)} \rangle_t &= \rho_{ZZ} dt, \\
d\langle \tilde{W}^{(Y)}, \tilde{W}^{(Z)} \rangle_t &= \rho_{YZ} dt.
\end{align*}
\]

For fixed time \( T > 0 \), our objective is to find the joint (risk-neutral) survival probability

\[
u^{\delta}(t, x, y, z) \equiv \tilde{\mathbb{P}} \left\{ \tau_t^{(1)} > T, \ldots, \tau_t^{(n)} > T \mid X_t = x, Y_t = y, Z_t = z \right\}, \tag{1}
\]
where \( t < T \), \( X_t \equiv (X_{t}^{(1)}, \ldots, X_{t}^{(n)}) \), \( x \equiv (x_1, \ldots, x_n) \), and \( \tau_i^{(t)} \) is the default time of firm \( i \), defined as follows,

\[
\tau_i^{(t)} = \inf \left\{ s \geq t, \ X_s^{(i)} \leq B_i(s) \right\},
\]

where \( B_i(t) \) is the exogenously pre-specified default threshold at time \( t \) for firm \( i \). Here we follow Black and Cox (1976) and we assume that \( B_i(t) = K_i e^{\eta_i t} \), with \( K_i > 0 \) and \( \eta_i \geq 0 \), all being constant numbers. It is very common that credit derivatives have long maturities. Therefore it is more realistic to assume time varying default thresholds (exponentially growing in our case) than constant ones. Observe that \( u^{\epsilon,\delta} \) is zero whenever \( x_i \leq B_i(t) \) for some \( i \) and therefore we only need to focus on the case where \( x_i > B_i(t) \) for all \( i = 1, 2, \ldots, n \).

3 Approximated Joint Survival Probabilities

We derive in this section an approximation for the joint survival probability \( u^{\epsilon,\delta} \) defined in (1). We first write a PDE representation for it and we then perform singular and regular perturbations with respect to the small parameters \( \epsilon \) and \( \delta \).

3.1 PDE Representation

In terms of partial differential equations (PDE), \( u^{\epsilon,\delta} \) is the solution to the following boundary value problem:

\[
\begin{align*}
L^{\epsilon,\delta} u^{\epsilon,\delta} &= 0, \quad x_i > B_i(t), \text{ for all } i, t < T, \\
u^{\epsilon,\delta}(t, x_1, x_2, \ldots, x_n, y, z) &= 0, \quad \exists i \in \{1, \ldots, n\}, x_i = B_i(t), t \leq T, \\
u^{\epsilon,\delta}(T, x_1, x_2, \ldots, x_n, y, z) &= 1, \quad x_i > B_i(t), \text{ for all } i,
\end{align*}
\]

where the operator \( L^{\epsilon,\delta} \) has the following decomposition in terms of powers of \( \sqrt{\epsilon} \) and \( \sqrt{\delta} \):

\[
L^{\epsilon,\delta} = \frac{1}{\epsilon} L_0 + \frac{1}{\sqrt{\epsilon}} L_1 + L_2 + \sqrt{\delta} M_1 + \delta M_2 + \sqrt{\delta/\epsilon} M_3,
\]

with the notations

\[
\begin{align*}
L_0 &= (m_Y - y) \frac{\partial}{\partial y} + \nu_Y^2 \frac{\partial^2}{\partial y^2}, \\
L_1 &= \nu_Y \sqrt{2} \left[ \sum_{i=1}^{n} \rho_i Y f_i(y, z) x_i \frac{\partial^2}{\partial x_i \partial y} - \Lambda_1(y, z) \frac{\partial}{\partial y} \right], \\
L_2 &= \frac{\partial}{\partial \epsilon} + \sum_{i=1}^{n} \left( \frac{1}{2} f_i^2(y, z) x_i^2 \frac{\partial^2}{\partial x_i^2} + r x_i \frac{\partial}{\partial x_i} \right),
\end{align*}
\]
\[ M_1 = \nu_Z \sqrt{2} \left[ \sum_{i=1}^{n} \rho_i z f_i(y, z) x_i \frac{\partial^2}{\partial x_i \partial z} - \Lambda_2(y, z) \frac{\partial}{\partial z} \right], \]
\[ M_2 = (m_Z - z) \frac{\partial}{\partial z} + \nu_Z^2 \frac{\partial^2}{\partial z^2}, \]
\[ M_3 = 2 \rho_Y \nu_Y \nu_Z \frac{\partial^2}{\partial y \partial z}. \]

As in Fouque et al. (2003), we expand \( u^{\varepsilon,\delta} \) in terms of powers of \( \sqrt{\varepsilon} \) and \( \sqrt{\delta} \):
\[ u^{\varepsilon,\delta} = u_0 + \sqrt{\varepsilon} u_{1,0} + \sqrt{\delta} u_{0,1} + \varepsilon u_{2,0} + \sqrt{\varepsilon \delta} u_{1,1} + \delta u_{0,2} + \cdots, \tag{4} \]
and retain
\[ \tilde{u} = u_0 + \sqrt{\varepsilon} u_{1,0} + \sqrt{\delta} u_{0,1} \tag{5} \]
as our approximation for \( u^{\varepsilon,\delta} \). In the Appendix A we present the formal expansion argument leading to the characterization of the leading order term \( u_0 \) and the two correction terms \( \sqrt{\varepsilon} u_{1,0} \) and \( \sqrt{\delta} u_{0,1} \). In the following sections we compute these terms in the context of our multidimensional boundary value problem.

### 3.2 Leading Order Term \( u_0 \)

Following Fouque et al. (2003) as explained in the Appendix A, the leading order term \( u_0 \) is independent of \( y \) and is determined by the following PDE system with respect to the variables \((t, x)\), the variable \( z \) being simply a parameter:
\[ \langle L_2 \rangle u_0 = 0, \quad x_i > B_i(t), \text{ for all } i, t < T, \]
\[ u_0(t, x_1, x_2, \ldots, x_n) = 0, \quad \exists i \in \{1, \ldots, n\}, x_i = B_i(t), t \leq T, \]
\[ u_0(T, x_1, x_2, \ldots, x_n) = 1, \quad x_i > B_i(t), \text{ for all } i, \tag{6} \]
where, from the definition (3) of \( \langle L_2 \rangle \), we have
\[ \langle L_2 \rangle = \frac{\partial}{\partial t} + \sum_{i=1}^{n} \left( \frac{1}{2} \left( f^2_i(\cdot, z) \right) x_i^2 \frac{\partial^2}{\partial x_i^2} + rx_i \frac{\partial}{\partial x_i} \right). \tag{7} \]

The variable \( z \) appears only as a parameter in the averaged diffusion coefficients \( \langle f_i^2(\cdot, z) \rangle \) with respect to the invariant distribution \( \mathcal{N}(m_Y, \nu_Y^2) \) of the process \( Y_t \) under the real world measure \( \mathbb{P} \), i.e.,
\[ \langle f_i^2(\cdot, z) \rangle = \int f_i^2(y, z) \frac{1}{\nu_Y \sqrt{2\pi}} \exp \left( -\frac{(y - m_Y)^2}{2\nu_Y^2} \right) dy. \]

**Proposition 1** The leading order term \( u_0 \) in the approximation (5) is given by:
\[ u_0 = \prod_{i=1}^{n} Q_i \equiv \prod_{i=1}^{n} \left[ N \left( d_{2(i)}^+ \right) - \left( \frac{x_i}{B_i(t)} \right)^{p_i} N \left( d_{2(i)}^- \right) \right], \tag{8} \]
where $N(\cdot)$ is the standard cumulative normal distribution function, and

\[ d_{2(i)}^\pm = \frac{\pm \ln \frac{x_i}{B_i(t)} + \left( r - \eta_i - \frac{\sigma^2(z)}{2} \right) (T - t)}{\sigma_i(z) \sqrt{T - t}}, \]

\[ \sigma_i(z) \equiv \sqrt{\langle f_i^2(z, z) \rangle}, \quad \text{(effective volatility of firm } i) \]

\[ p_i \equiv 1 - \frac{2(r - \eta_i)}{\sigma_i^2(z)}. \]

**Proof** From (6) and (7), $u_0$ admits the probabilistic representation:

\[ u_0 = \mathbb{E} \left\{ \prod_{i=1}^n \mathbf{1}_{\{ \inf_{t\leq s\leq T} \bar{X}_s^{(i)} / B_i(s) > 1\}} \mid \bar{X}_s = x \right\}, \]

where, under the probability measure $\mathbb{P}$, we have

\[ d\bar{X}_t^{(1)} = r\bar{X}_t^{(1)} dt + \sigma_1(z)\bar{X}_t^{(1)} d\tilde{W}_t^{(1)}, \]

\[ d\bar{X}_t^{(2)} = r\bar{X}_t^{(2)} dt + \sigma_2(z)\bar{X}_t^{(2)} d\tilde{W}_t^{(2)}, \]

\[ \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \]

\[ d\bar{X}_t^{(n)} = r\bar{X}_t^{(n)} dt + \sigma_n(z)\bar{X}_t^{(n)} d\tilde{W}_t^{(n)}, \]

with $\tilde{W}^{(i)}$'s being independent standard Brownian motions. In other words, $\{\bar{X}_t^{(i)}\}, i = 1, 2, \ldots, n,$ are independent Geometric Brownian motions and it follows that

\[ u_0 = \prod_{i=1}^n \mathbb{P} \left\{ \inf_{t\leq s\leq T} \bar{X}_s^{(i)} / B_i(s) > 1 \mid \bar{X}_t^{(i)} = x_i \right\}. \]

By doing change of variables to make the corresponding boundary constant (instead of exponentially growing) and then using the appropriate formula in Borodin and Salminen (2002) obtained by the method of images or equivalently the reflection principle in one dimension, one can reach the conclusion in the proposition.

### 3.3 Correction Term $\sqrt{t} u_{1,0}$

From Appendix A the term $u_{1,0}$ is determined by the following PDE system:

\[ \langle \mathcal{L}_2 \rangle u_{1,0} = \mathcal{A} u_0, \quad x_i > B_i(t), \text{ for all } i, t < T, \]

\[ u_{1,0}(t, x_1, x_2, \ldots, x_n) = 0, \quad \exists i \in \{1, \ldots, n\}, x_i = B_i(t), t \leq T, \]

\[ u_{1,0}(T, x_1, x_2, \ldots, x_n) = 0, \quad x_i > B_i(t), \text{ for all } i, \]

where the operator $\mathcal{A}$ is given by

\[ \mathcal{A} \equiv \langle \mathcal{L}_1 \mathcal{L}_0^{-1}(\mathcal{L}_2 - \langle \mathcal{L}_2 \rangle) \rangle \]

\[ = \frac{\nu}{\sqrt{2}} \sum_{i=1}^n \sum_{j=1}^n \rho_{ij} \left\langle f_j \frac{\partial \phi_j}{\partial y} \right\rangle x_i \frac{\partial}{\partial x_i} \left( x_j^2 \frac{\partial^2}{\partial x_j^2} \right) - \sum_{j=1}^n \left\langle \Lambda_j \frac{\partial \phi_j}{\partial y} \right\rangle x_j^2 \frac{\partial^2}{\partial x_j^2} \]

\[ = -\nu \sum_{i=1}^n \sum_{j=1}^n \rho_{ij} \left\langle f_j \frac{\partial \phi_j}{\partial y} \right\rangle x_i \frac{\partial}{\partial x_i} \left( x_j^2 \frac{\partial^2}{\partial x_j^2} \right) - \sum_{j=1}^n \left\langle \Lambda_j \frac{\partial \phi_j}{\partial y} \right\rangle x_j^2 \frac{\partial^2}{\partial x_j^2} \]
Here \( \phi_i(y, z) \), for \( i = 1, 2, \ldots, n \), denote solutions of reasonable growth at infinity to the following Poisson equations with respect to the variable \( y \):

\[
\mathcal{L}_0 \phi_i(y, z) = f_i^2(y, z) - \langle f_i^2(\cdot, z) \rangle,
\]

and \( \langle \cdot \rangle \) denotes the average with respect to the invariant distribution \( \mathcal{N}(m_Y, \nu_Z^2) \) of \( Y \).

The following result shows that the multi-dimensional problem (9) can be reduced to many uncoupled one- and two-dimensional problems.

**Proposition 2** The correction term \( \sqrt{e} u_{1,0} \) is given by

\[
\sqrt{e} u_{1,0} = \sum_{i=1}^{n} R_i^{(2)} w_i^{(2)} \prod_{j=1}^{n} Q_j + \sum_{i=1}^{n} R_i^{(3)} w_i^{(3)} \prod_{j=1}^{n} Q_j + \sum_{i,j=1}^{n} R_{ij}^{(3)} w_{ij}^{(3)} \prod_{k=1}^{n} Q_k,
\]

where the coefficients \( R_i^{(2)}, R_i^{(3)}, R_{ij}^{(3)} \) depend on the parameter \( z \) and are given by

\[
R_i^{(2)} = \frac{-\nu_Y \sqrt{e}}{\sqrt{2}} \mathcal{A}(\cdot, z) \frac{\partial \phi_i}{\partial y}(\cdot, z),
\]

\[
R_i^{(3)} = \frac{\nu_Y \sqrt{e}}{\sqrt{2}} \rho_Y \mathcal{A}(\cdot, z) \frac{\partial \phi_i}{\partial y}(\cdot, z),
\]

\[
R_{ij}^{(3)} = \frac{\nu_Y \sqrt{e}}{\sqrt{2}} \rho_Y \mathcal{A}(\cdot, z) \frac{\partial \phi_j}{\partial y}(\cdot, z), \quad i \neq j,
\]

with \( \phi_i \)'s given by (11) and \( Q_i \)'s given in Proposition 1, and where the functions \( w_i^{(2)}(t, x_i), w_i^{(3)}(t, x_i) \) and \( w_{ij}^{(3)}(t, x_i, x_j) \) depend on the parameter \( z \) and are given by the following problems:

\[
\frac{\partial}{\partial t} + \frac{1}{2} \sigma_i^2(z)x_i^2 \frac{\partial^2}{\partial x_i^2} + r x_i \frac{\partial}{\partial x_i} \right] w_i^{(2)} = x_i \frac{\partial^2 Q_i}{\partial x_i^2}, \quad x_i > B_i(t), t < T,
\]

\[
w_i^{(2)}(t, B_i(t)) = 0, \quad t \leq T,
\]

\[
w_i^{(2)}(T, x_i) = 0, \quad x_i > B_i(t),
\]

\[
\frac{\partial}{\partial t} + \frac{1}{2} \sigma_i^2(z)x_i^2 \frac{\partial^2}{\partial x_i^2} + r x_i \frac{\partial}{\partial x_i} \right] w_i^{(3)} = x_i \frac{\partial}{\partial x_i} \left( x_i \frac{\partial^2 Q_i}{\partial x_i^2} \right), \quad x_i > B_i(t), t < T,
\]

\[
w_i^{(3)}(t, B_i(t)) = 0, \quad t \leq T,
\]

\[
w_i^{(3)}(T, x_i) = 0, \quad x_i > B_i(t),
\]
where the operator \( \langle M \rangle \) satisfied. The boundary and terminal conditions for the correction

From Appendix A the term \( u \) is given by:

\[
\sqrt{\epsilon} A = \sum_{i=1}^{n} R_i^{(2)} x_i^2 \frac{\partial^2}{\partial x_i^2} + \sum_{i=1}^{n} R_i^{(3)} x_i \frac{\partial}{\partial x_i} \left( x_i^2 \frac{\partial^2}{\partial x_i^2} \right) + \sum_{i,j=1, j \neq i}^{n} R_{ij}^{(3)} x_i \frac{\partial}{\partial x_i} \left( x_j^2 \frac{\partial^2}{\partial x_j^2} \right).
\]

By linearity of (9), it is enough to check that

\[
\langle L_2 \rangle \left( w_i^{(2)} \prod_{j=1, j \neq i}^{n} Q_j \right) = x_i^2 \frac{\partial^2 u_0}{\partial x_i^2},
\]

\[
\langle L_2 \rangle \left( w_i^{(3)} \prod_{j=1, j \neq i}^{n} Q_j \right) = x_i \frac{\partial}{\partial x_i} \left( x_i^2 \frac{\partial^2 u_0}{\partial x_i^2} \right),
\]

\[
\langle L_2 \rangle \left( w_{ij}^{(3)} \prod_{k=1, k \neq i,j}^{n} Q_k \right) = x_i \frac{\partial}{\partial x_i} \left( x_j^2 \frac{\partial^2 u_0}{\partial x_j^2} \right).
\]

Using the form (7) of \( \langle L_2 \rangle \) and \( u_0 = \prod_{i=1}^{n} Q_i \) one can easily check that (19), (20), and (21) are satisfied. The boundary and terminal conditions for the correction \( \sqrt{\epsilon} u_{1,0} \) are directly inherited from the boundary and terminal conditions for the functions \( w_i^{(2)} \)’s, \( w_i^{(3)} \)’s, \( w_{ij}^{(3)} \)’s, and \( Q_i \)’s.

The problems (16), (17) and (18) are boundary value problems with sources. In Appendix B we show how to transform them into boundary value problems without source leading to explicit formulas (up to Gaussian integrals).

### 3.4 Correction Term \( \sqrt{\epsilon} u_{0,1} \)

From Appendix A the term \( u_{0,1} \) is determined by the following PDE system:

\[
\langle L_2 \rangle u_{0,1} = -\langle M_1 \rangle u_0, \quad x_i > B_i(t), \text{ for all } i, t < T,
\]

\[
u_{Z} \sqrt{2} \left[ \sum_{i=1}^{n} \rho_i Z(f_i(\cdot, z)) x_i \frac{\partial^2}{\partial x_i \partial z} - \langle \Lambda_2(\cdot, z) \rangle \frac{\partial}{\partial z} \right].
\]

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The following result shows that, as for \( u_{1,0} \), the multi-dimensional problem (22) for \( u_{0,1} \) can be reduced to many uncoupled one- and two-dimensional problems.

**Proposition 3** The correction term \( \sqrt{\sigma} u_{0,1} \) is given by

\[
\sqrt{\sigma} u_{0,1} = \sum_{i=1}^{n} R_i^{(0)} w_i^{(0)} \prod_{j \neq i} Q_j + \sum_{i=1}^{n} R_i^{(1)} w_i^{(1)} \prod_{j \neq i} Q_j + \sum_{i,j=1, i \neq j}^{n} R_{ij}^{(1)} w_{ij}^{(1)} \prod_{k \neq i,j} Q_k, \tag{23}
\]

where the coefficients \( R_i^{(0)}, R_i^{(1)}, R_{ij}^{(1)} \) depend on the parameter \( z \) and are given by

\[
R_i^{(0)} = -\nu_{Z} \sqrt{2} \delta (\Lambda_2(\cdot, z)) \sigma_i'(z) \tag{24}
\]

\[
R_i^{(1)} = \nu_{Z} \sqrt{2} \delta \rho_{Z}(f_i(\cdot, z)) \sigma_i'(z) \tag{25}
\]

\[
R_{ij}^{(1)} = \nu_{Z} \sqrt{2} \delta \rho_{Z}(f_i(\cdot, z)) \sigma_j'(z), \quad i \neq j \tag{26}
\]

\( \sigma_i(z) \)'s and \( Q_i \)'s given in Proposition 1, \( \sigma_i' = d\sigma_i/dz \), and where the functions \( w_i^{(0)}(t, x_i; z) \), \( w_i^{(1)}(t, x_i; z) \) and \( w_{ij}^{(1)}(t, x_i, x_j; z) \) depend on the parameter \( z \) and are given by the following problems:

\[
\left[ \frac{\partial}{\partial t} + \frac{1}{2} \sigma_i^2(z)x_i^2 \frac{\partial^2}{\partial x_i^2} + rx_i \frac{\partial}{\partial x_i} \right] w_i^{(0)}(t) = -\frac{\partial Q_i}{\partial \sigma_i}, \quad x_i > B_i(t), t < T, \tag{27}
\]

\[
w_i^{(0)}(t, B_i(t)) = 0, \quad t \leq T, \quad w_i^{(0)}(T, x_i) = 0, \quad x_i > B_i(t),
\]

\[
\left[ \frac{\partial}{\partial t} + \frac{1}{2} \sigma_i^2(z)x_i^2 \frac{\partial^2}{\partial x_i^2} + rx_i \frac{\partial}{\partial x_i} \right] w_i^{(1)}(t) = -x_i \frac{\partial}{\partial x_i} \left( \frac{\partial Q_i}{\partial \sigma_i} \right), \quad x_i > B_i(t), t < T, \tag{28}
\]

\[
w_i^{(1)}(t, B_i(t)) = 0, \quad t \leq T, \quad w_i^{(1)}(T, x_i) = 0, \quad x_i > B_i(t),
\]

\[
\left[ \frac{\partial}{\partial t} + \frac{1}{2} \sigma_i^2(z)x_i^2 \frac{\partial^2}{\partial x_i^2} + \frac{1}{2} \sigma_j^2(z)x_j^2 \frac{\partial^2}{\partial x_j^2} + rx_i \frac{\partial}{\partial x_i} + rx_j \frac{\partial}{\partial x_j} \right] w_{ij}^{(1)}(t) = -\left( x_i \frac{\partial Q_i}{\partial x_i} \right) \left( x_j \frac{\partial Q_j}{\partial \sigma_j} \right), \tag{29}
\]

\[
w_{ij}^{(1)}(t, x_i, x_j) = 0, \quad \text{if } x_i = B_i(t) \quad \text{or} \quad x_j = B_j(t), t \leq T, \quad w_{ij}^{(1)}(T, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t).
\]

**Proof** The proof is very similar to that of Proposition 2. Since \( u_0 \) depends on \( z \) only through \( \sigma_i(z) \)'s, we have

\[
\frac{\partial u_0}{\partial z} = \sum_{j=1}^{n} \sigma_j'(z) \frac{\partial u_0}{\partial \sigma_j},
\]

\[9\]
and therefore

\[
\sqrt{\delta}(\mathcal{M}_1)u_0 = \nu_Z \sqrt{2\delta} \left[ \sum_{i=1}^{n} \rho_i \zeta (f_i,'z) x_i \frac{\partial}{\partial x_i} \left( \sum_{j=1}^{n} \sigma'_j(z) \frac{\partial u_0}{\partial \sigma_j} \right) - \langle \Lambda_2('z) \rangle \sum_{j=1}^{n} \sigma'_j(z) \frac{\partial u_0}{\partial \sigma_j} \right]
\]

\[
= \nu_Z \sqrt{2\delta} \left[ \sum_{i=1}^{n} \sum_{j=1}^{n} \rho_i \zeta (f_i,'z) \sigma'_j(z) x_i \frac{\partial}{\partial x_i} \left( \frac{\partial u_0}{\partial \sigma_j} \right) - \langle \Lambda_2('z) \rangle \sum_{i=1}^{n} \sigma'_i(z) \frac{\partial u_0}{\partial \sigma_i} \right]
\]

\[
= \sum_{i=1}^{n} R_i^{(0)} \frac{\partial u_0}{\partial \sigma_i} + \sum_{i=1}^{n} R_i^{(1)} x_i \frac{\partial}{\partial x_i} \left( \frac{\partial u_0}{\partial \sigma_i} \right) + \sum_{i,j=1}^{n} R_{ij}^{(1)} x_i \frac{\partial}{\partial x_i} \left( \frac{\partial u_0}{\partial \sigma_j} \right),
\]

where we have used the definitions (24, 25, 26) of \((R_i^{(0)}, R_i^{(1)}, R_{ij}^{(1)})\). By linearity of (22), it is enough to check that

\[
\langle L_2 \rangle \left( w_{i}^{(1)} \prod_{j=1,j \neq i}^{n} Q_j \right) = - \frac{\partial u_0}{\partial \sigma_i}, \tag{30}
\]

\[
\langle L_2 \rangle \left( w_{i}^{(1)} \prod_{j=1,j \neq i}^{n} Q_j \right) = - x_i \frac{\partial}{\partial x_i} \left( \frac{\partial u_0}{\partial \sigma_i} \right), \tag{31}
\]

\[
\langle L_2 \rangle \left( \prod_{k=1,k \neq i,j}^{n} Q_k \right) = - x_i \frac{\partial}{\partial x_i} \left( \frac{\partial u_0}{\partial \sigma_j} \right). \tag{32}
\]

Using the form (7) of \(\langle L_2 \rangle\) and \(u_0 = \prod_{i=1}^{n} Q_i\) one can easily check that (30), (31), and (32) are satisfied. The boundary and terminal conditions for the correction \(\sqrt{\delta} u_{0,1}\) are directly inherited from the boundary and terminal conditions for the functions \(w_{i}^{(0)}\)'s, \(w_{i}^{(1)}\)'s, \(w_{ij}^{(1)}\)'s, and \(Q_i\)'s.

As for (16), (17) and (18) we show in Appendix B that the boundary value problems with sources (27), (28), and (29) for \(w_{i}^{(0)}\)'s, \(w_{i}^{(1)}\)'s, \(w_{ij}^{(1)}\)'s can be transformed into boundary value problems without source leading to explicit formulas (up to Gaussian integrals).

### 3.5 Summary of the Approximation

Combining the results of Propositions 1, 2 and 3 we get that the approximation \(\tilde{u}\) in (5) is given by

\[
\tilde{u} = \prod_{i=1}^{n} Q_i + \sum_{i=1}^{n} R_i^{(2)} x_i \prod_{j=1,j \neq i}^{n} Q_j + \sum_{i=1}^{n} R_i^{(3)} x_i \prod_{j=1,j \neq i}^{n} Q_j + \sum_{i,j=1}^{n} R_{ij}^{(3)} x_i \prod_{k=1,k \neq i,j}^{n} Q_k
\]

\[
+ \sum_{i=1}^{n} R_i^{(0)} x_i \prod_{j=1,j \neq i}^{n} Q_j + \sum_{i=1}^{n} R_i^{(1)} x_i \prod_{j=1,j \neq i}^{n} Q_j + \sum_{i,j=1}^{n} R_{ij}^{(1)} x_i \prod_{k=1,k \neq i,j}^{n} Q_k, \tag{33}
\]

\[
10
\]
where \((R_{i}^{(2)}, R_{i}^{(3)}, R_{ij})\) are small of order \(\sqrt{\epsilon}\), \((R_{i}^{(0)}, R_{i}^{(1)}, R_{ij}^{(1)})\) are small of order \(\sqrt{\delta}\), and they all depend on the parameter \(z\). The functions \(Q_{i}, w_{i}^{(2)}, w_{i}^{(3)}, w_{i}^{(0)}, w_{i}^{(1)}\) depend on the variable \(x_{i}\), the functions \(w_{ij}^{(3)}, w_{ij}^{(1)}\) depend on the variables \((x_{i}, x_{j})\), and they all depend on the parameter \(z\). The accuracy of approximation (33) is given at the end of Appendix A.

**Remark** The (approximated) survival probability of a single bond/firm (treated in Fouque et al. (2006)) is a particular case of the result (33). It can be obtained by fixing an index and eliminating all those terms that involve any one of the other indices, which includes all the two-index cross-terms. For example, the (approximated) survival probability of bond 1 only involves \(Q_{1}, w_{1}^{(0)}, w_{1}^{(1)}, w_{1}^{(2)}\) and \(w_{1}^{(3)}\).

4 Loss Distribution

We consider now a portfolio consisting of \(N\) defaultable bonds and we denote by \(a_{i}\) the number of bond \(i\) in this portfolio. Assuming zero recovery rate from default for each bond, the loss at time \(t\) of this portfolio is given by the random variable

\[
L(t) \equiv \sum_{i=1}^{N} a_{i} \chi_{i}(t),
\]

where \(\chi_{i}(t)\) takes on 1 if bond \(i\) defaults before \(t\) and 0 otherwise. Our objective is to study the distribution of \(L(T)\) for a maturity \(T\) smaller than all the bond maturities.

4.1 General Case

Since the portfolio consists only of a finite number of bonds, \(L\) must have a discrete distribution function. It hence suffices to find the probability value that a subset of names in the portfolio default. It turns out that this can be done recursively. For example,

\[
P^{*}\{\text{only bond 1 defaults in the portfolio before time } T\}
\]

\[
= P^{*}\{\tau_{1} \leq T, \tau_{2} > T, \cdots, \tau_{N} > T\}
\]

\[
= P^{*}\{\tau_{2} > T, \cdots, \tau_{N} > T\} - P^{*}\{\tau_{1} > T, \tau_{2} > T, \cdots, \tau_{N} > T\},
\]

while \(\tau_{i}\) is the default time of bond \(i\). Both terms on the right hand side of the last equality are known (approximately) by formula (33). In general, if we denote

\[
I \equiv \{i_{1}, i_{2}, \ldots, i_{n}\} \subset J \equiv \{j_{1}, j_{2}, \ldots, j_{m}\} \subset \bar{N} \equiv \{1, 2, \ldots, N\},
\]

\[
D_{|J|}^{n} (I; J) \equiv P^{*}\{(\text{bond } i \text{ defaults, } i \in I) \cap (\text{bond } j \text{ survives, } j \in J \setminus I)\},
\]

then

\[
D_{m}^{n} (\{i_{1}, \ldots, i_{n}\}; J) = P^{*}\{(\tau_{i} \leq T, i \in \{i_{1}, \ldots, i_{n-1}, i_{n}\}) \cap (\tau_{j} > T, j \in J \setminus I)\}
\]

\[
= P^{*}\{(\tau_{i} \leq T, i \in \{i_{1}, \ldots, i_{n-1}\}) \cap (\tau_{j} > T, j \in J \setminus I)\} - P^{*}\{(\tau_{i} \leq T, i \in \{i_{1}, \ldots, i_{n-1}\}) \cap (\tau_{j} > T, j \in J \setminus \{i_{1}, \ldots, i_{n-1}\})\}.
\]
Therefore,

\[
D^n_m \left( \{i_1, \ldots, i_n \}; \{j_1, \ldots, j_m \} \right) = D^{n-1}_{m-1} \left( \{i_1, \ldots, i_{n-1} \}; \{j_1, \ldots, j_m \} \backslash \{i_n \} \right) - D^{n-1}_{m-1} \left( \{i_1, \ldots, i_{n-1} \}; \{j_1, \ldots, j_m \} \right).
\] (34)

Formula (34) is recursive and by implementing it once, one can reduce by one the superscript \(n\) (= the number of defaults) on \(D\). This can be done repeatedly until one reduces the superscript to zero, implying a total survival of an appropriate subset of names in the portfolio. Finally the probability of total survival is (approximately) \(\tilde{u}\) given by (33), with names/indices \(\{1, 2, \ldots, n\}\) replaced by the appropriate set of indices/names.

It can be shown that in order to compute \(D^n_m(\cdot, \cdot)\), one has to evaluate \(\tilde{u}\)-like forms \(2^n\) times. This may be computationally expensive for a portfolio of big size, say 50 names or more. For a smaller size portfolio, say \(N = 20\), however, the computational cost is acceptable to find for instance the probability of 50% loss, namely \(D^{10}_{20}(\cdot, \cdot)\).

### 4.2 Special Case: Homogeneous Portfolio

We now consider a fully homogeneous portfolio, that is

\[
f_i(y, z) = f(y, z), \quad \rho_{iY} = \rho_Y, \quad \rho_{iZ} = \rho_Z, \quad a_i = a, \quad X^{(i)}_0 = x_i = x,
\] (35)

for all \(i = 1, \ldots, N\). We first recall a classical result.

**Lemma 1** Let \(\tau_i\) be the default time of bond \(i\), and suppose that under a probability \(\mathbb{P}\)

\[
\mathbb{P}(\tau_i > T, i \in \{i_1, i_2, \ldots, i_m\}) = \mathbb{P}(\tau_j > T, j \in \{j_1, j_2, \ldots, j_m\}),
\]

for any two equal-size sets of indices \(\{i_1, i_2, \ldots, i_m\}\) and \(\{j_1, j_2, \ldots, j_m\}\) chosen from \(\{1, 2, \ldots, N\}\) with \(1 \leq m \leq N\). Define

\[
S_m \equiv \mathbb{P}(\tau_i > T, i \in \{1, 2, \ldots, m\}), \quad 1 \leq m \leq N.
\] (36)

Then, for \(0 \leq k < N\), the probability that exactly \(k\) bonds, among the \(N\) bonds, default before \(T\) is given by

\[
F^{(N)}_k \equiv \mathbb{P} \left( \sum_{i=1}^{N} \chi_i(T) = k \right) = \binom{N}{k} \sum_{j=0}^{k} \binom{k}{j} (-1)^j S_{N+j-k}.
\] (37)

**Proof** We provide here a short proof which consists in computing the moment generating function of the number of survivals. Denote by \(\chi'_i \equiv 1 - \chi_i\) the event “firm \(i\) survives after \(T\).”

On one hand we have

\[
\Phi(z) \equiv \mathbb{E} \left( z^{(\sum_{i=1}^{N} \chi'_i)} \right) = \mathbb{E} \left( z^{(N-\sum_{i=1}^{N} \chi_i)} \right) = \sum_{k=0}^{N} z^{(N-k)} F^{(N)}_k = \sum_{k=0}^{N} z^k F^{(N)}_{N-k}.
\] (38)
On the other hand we have

$$\Phi(z) = \mathbb{E}\left( \prod_{i=1}^{N} z^{\chi'_i} \right) = \mathbb{E}\left( \prod_{i=1}^{N} (1 + (z-1)\chi'_i) \right) = \mathbb{E}\left( \sum_{(i_1,\ldots,i_n),n=0,\ldots,N} (z-1)^n \chi'_{i_1} \cdots \chi'_{i_n} \right)$$

$$= \sum_{n=0}^{N} (z-1)^n \sum_{(i_1,\ldots,i_n)} \mathbb{P}(\tau_i > T, i \in \{i_1, i_2, \ldots, i_n\}) = \sum_{n=0}^{N} (z-1)^n \binom{N}{n} S_n$$

$$= \sum_{n=0}^{N} \binom{n}{k} (-1)^{n-k} \binom{n}{k} \binom{N}{n} S_n$$

$$= \sum_{k=0}^{N} z^k \binom{n}{k} (-1)^{n-k} \binom{n}{k} \binom{N}{n} S_n.$$  \hspace{1cm} \text{(39)}

The function \(\Phi(z)\) being the polynomial in \(z\) given by (38) and (39) we deduce that

$$F_{N-k}^{(N)} = \sum_{n=k}^{N} (-1)^{n-k} \binom{n}{k} \binom{N}{n} S_n = \binom{N}{N-k} \sum_{n=k}^{N} (-1)^{n-k} \binom{N-k}{n-k} S_n.$$  

We finally obtain (37):

$$F_k^{(N)} = \binom{N}{k} \sum_{n=N-k}^{N} (-1)^{n-k} \binom{k}{n-k} S_n$$

$$= \binom{N}{k} \sum_{j=0}^{k} (-1)^j \binom{k}{j} S_{N-k+j},$$

by setting \(j = n - N + k\).

With the homogeneity assumption, we set \(q \equiv Q_1(t,x)\) for the survival probability after \(t\) of one given bond, and we obtain from the results in Section 3 that

$$u_0 = \prod_{i=1}^{n} Q_i = q^n,$$

$$\begin{align*}
\sqrt{\epsilon} u_{1,0} &= \sum_{i=1}^{n} R_i^{(2)} w_i^{(2)} \prod_{j=1}^{n} Q_j + \sum_{i=1}^{n} R_i^{(3)} w_i^{(3)} \prod_{j=1}^{n} Q_j + \sum_{i,j=1}^{n \neq i} R_{ij}^{(3)} w_{ij}^{(3)} \prod_{k=1}^{n \neq i,j} Q_k \\
&= n R_1^{(2)} w_1^{(2)}(t,x) q^{n-1} + n R_1^{(3)} w_1(t,x)^{(3)} q^{n-1} + n(n-1) R_{12}^{(3)} w_{12}^{(3)}(t,x) q^{n-2},
\end{align*}$$

$$\sqrt{\delta} u_{0,1} = \sum_{i=1}^{n} R_i^{(0)} w_i^{(0)} \prod_{j=1}^{n} Q_j + \sum_{i=1}^{n} R_i^{(1)} w_i^{(1)} \prod_{j=1}^{n} Q_j + \sum_{i,j=1}^{n \neq i} R_{ij}^{(1)} w_{ij}^{(1)} \prod_{k=1}^{n \neq i,j} Q_k$$

$$= n R_1^{(0)} w_1^{(0)}(t,x) q^{n-1} + n R_1^{(1)} w_1(t,x)^{(1)} q^{n-1} + n(n-1) R_{12}^{(1)} w_{12}^{(1)}(t,x) q^{n-2},$$

where we have used the fact that the \(R\)’s and \(w\)’s do not depend on a particular choice of names \((i, j)\).
We define the quantities

\[ A \equiv \sum_{k=0}^{3} R_{11}^{(k)} w_{11}^{(k)} (t, x), \]  
\[ B \equiv R_{12}^{(1)} w_{12}^{(1)} (t, x, x) + R_{12}^{(3)} w_{12}^{(3)} (t, x, x), \]

which also depend on the parameter \( z \), and we rewrite the joint survival probabilities (36) as

\[ S_n \approx \tilde{u} \equiv u_0 + \sqrt{\epsilon} u_{1,0} + \sqrt{\delta} u_{0,1} = q^n + Anq^{n-1} + Bn(n-1)q^{n-2}, \quad n \geq 2. \]

Note that \( S_1 = q + A \), and hence the previous formula for \( S_n \) is actually valid for all \( n \geq 1 \), as well as for \( n = 0 \) with \( S_0 \equiv 1 \).

The approximated loss distribution is now given by

\[
\mathbb{P}^s (L = k) = \binom{N}{k} \sum_{j=0}^{k} \binom{k}{j} (-1)^j S_{N+j-k} = \binom{N}{k} \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} S_{N-i}
\]
\[
\approx \binom{N}{k} \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} [q^{N-i} + A(N-i)q^{N-i-1} + B(N-i)(N-i-1)q^{N-i-2}]
\]
\[
= \binom{N}{k} \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} q^{N-i} + A \binom{N}{k} \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} (N-i)q^{N-i-1}
\]
\[
+ B \binom{N}{k} \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} (N-i)(N-i-1)q^{N-i-2}
\]
\[
\equiv I_0 + AI_1 + BI_2,
\]

where \( I_0, I_1, \) and \( I_2 \) are obtained by straightforward calculation:

\[
I_0 = \binom{N}{k} \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} q^{N-i} = \binom{N}{k} (1-q)^k q^{N-k}, \tag{42}
\]
\[
I_1 = \binom{N}{k} \left[ \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} s^{N-i} \right] \bigg|_{s=q} = \binom{N}{k} \left[ s^{N-k}(1-s)^k \right] \bigg|_{s=q}
\]
\[
= \left[ \frac{N-k}{q} - \frac{k}{1-q} \right] I_0, \tag{43}
\]
\[
I_2 = \binom{N}{k} \left[ \sum_{i=0}^{k} \binom{k}{i} (-1)^{k-i} s^{N-i} \right] \bigg|_{s=q} = \binom{N}{k} \left[ s^{N-k}(1-s)^k \right] \bigg|_{s=q}
\]
\[
= \binom{N}{k} \left[ (N-k)(N-k-1)q^{N-k-2}(1-q)^k - 2k(N-k)q^{N-k-1}(1-q)^{k-1}
\]
\[
+ k(k-1)q^{N-k}(1-q)^{k-2} \right] \bigg|_{s=q}
\]
\[
= \left[ \frac{(N-k)(N-k-1)}{q^2} - \frac{2k(N-k)}{q(1-q)} + \frac{k(k-1)}{(1-q)^2} \right] I_0. \tag{44}
\]
To summarize, for $0 \leq k < N$,

$$\mathbb{P}^*(L = k) \approx I_0 + AI_1 + BI_2,$$

(45)

where $I_0, I_1$ and $I_2$ are explicitly given by (42, 43, 44), and $A$ and $B$ defined in (40, 41) are small of order $\max\{\sqrt{\epsilon}, \sqrt{\delta}\}$.

Note that $I_0$ corresponds to the case where all the underlying assets are mutually independent, which gives rise to the classic binomial distribution. Since the method used in this paper is perturbation, we call (45) the perturbed binomial formula.

4.3 Numerical Illustration

For the homogeneous portfolio case discussed above, we implemented some numerical computation to see the effect of introducing stochastic volatilities.

![Figure 1: Perturbed Binomial Loss Distribution](image)

The parameters used in Figure 1 are as follows:

$$N = 100, \quad q = 0.9, \quad A = 0.00, \quad B = 0.0006.$$ 

The upper graph presents the probability mass function and the lower one presents the cumulative distribution function for the loss. Note that in order to make comparison between our result and
the classic binomial distribution, we chose $A = 0$ because a non-zero $A$ would make single name survival probabilities distinct under these two scenarios. By choosing $A = 0$, the single name survival probability is $q = 0.9 = 90\%$. Note also that $B$ is chosen very small to ensure that the approximation is in its range of validity.

It can be observed from Figure 1 that:

- the probability, with stochastic volatilities, that the total portfolio loss is less than 3% is bigger than that from the classic binomial distribution;
- the probability, with stochastic volatilities, that the total portfolio loss is bigger than 15% is bigger than that from the classic binomial distribution.

In terms of CDO tranches (we refer to Duffie and Singleton (2003) for an introduction), this implies that the expected loss and hence the fair spread of the equity tranche become less, while the expected loss and hence the fair spread of the senior tranche become bigger, than in the classic binomial case. This phenomenon is consistent with what has been documented so far in CDO literature if one increases the default correlation between the underlying bonds and keeps other things unchanged. For example, see Duffie and Garleanu (2001). Note that a positive number $B$ indicates positive correlation between the underlying bonds. Here we assume that the equity tranche absorbs 0-3% loss and the senior absorbs 15%-100% loss.

Furthermore, the binomial probability mass function achieves its maximum 0.1319 at $k = 11$, while the probability mass function with stochastic volatilities achieves its maximum 0.1047 at $k = 8$.

5 Models with Name-Name Correlation

We now consider the correlated case, namely where the Brownian motions $\tilde{W}^{(i)}$s driving the names are correlated. Using the notation of Section 2, this means taking $d\langle \tilde{W}^{(i)}, \tilde{W}^{(j)} \rangle_t = \rho_{ij} dt$ for $i \neq j$ under the risk-neutral probability measure $\tilde{P}$ with $|\rho_{ij}| < 1$. Observe that for non-zero $\rho_{ij}$'s the conditions $\sum_{i=1}^n \rho_{iY}^2 \leq 1$ and $\sum_{i=1}^n \rho_{iZ}^2 \leq 1$ are no longer needed. We denote by $u^{\epsilon, \delta, \rho}$ the joint survival probability defined by

$$u^{\epsilon, \delta, \rho}(t, x, y, z) \equiv \tilde{P} \{ \tau^{(1)}_t > T, \ldots, \tau^{(n)}_t > T \mid X_t = x, Y_t = y, Z_t = z \}.$$  \hspace{1cm} (46)

In terms of PDEs, $u^{\epsilon, \delta, \rho}$ is the solution to the boundary value problem

$$L^{\epsilon, \delta, \rho} u^{\epsilon, \delta, \rho} = 0, \quad x_i > B_i(t), \text{ for all } i, t < T,$$
$$u^{\epsilon, \delta, \rho}(t, x_1, x_2, \ldots, x_n, y, z) = 0, \quad \exists i \in \{1, \cdots, n\}, x_i = B_i(t), t \leq T,$$
$$u^{\epsilon, \delta, \rho}(T, x_1, x_2, \ldots, x_n, y, z) = 1, \quad x_i > B_i(t), \text{ for all } i,$$

where the operator $L^{\epsilon, \delta, \rho}$ can be written as

$$L^{\epsilon, \delta, \rho} = L^{\epsilon, \delta} + \sum_{i<j}^n \rho_{ij} L^{(ij)}_{\rho},$$  \hspace{1cm} (47)
where we have used $\rho_{ij} = \rho_{ji}$, the definition (2) of the operator $L^{\epsilon,\delta}$, and the notation
\begin{equation}
L^{(ij)}_\rho = f_i(y, z) f_j(y, z) x_i x_j \frac{\partial^2}{\partial x_i \partial x_j}.
\end{equation}

The leading order term in the small $\epsilon$ and small $\delta$ expansion carried out in the previous sections would correspond to the correlated multi-name case with constant volatility. As explained in the introduction this is not a tractable model because of the lack of simple formulas for the joint distribution of hitting times. This leads us to perform an additional expansion around the independent case where the $\rho_{ij}$’s are zero. We therefore consider the case where the $\rho_{ij}$’s are small and of the same order.

Expanding $u^{\epsilon,\delta,\rho}$ in powers of $\sqrt{\epsilon}$, $\sqrt{\delta}$, and $\rho_{ij}$ we get:
\begin{equation}
u^{\epsilon,\delta,\rho} = u^{\epsilon,\delta} + \sum_{i<j} \rho_{ij} \left( u^{(ij)}_{0,0,1} + \sqrt{\epsilon} u^{(ij)}_{1,0,1} + \sqrt{\delta} u^{(ij)}_{0,1,1} + \cdots \right) + \cdots,
\end{equation}
and retain the lowest order terms,
\begin{equation}
\tilde{u} \equiv u_0 + \sqrt{\epsilon} u_{1,0} + \sqrt{\delta} u_{0,1} + \sum_{i<j} \rho_{ij} u^{(ij)}_{0,0,1},
\end{equation}
as our approximation for $u^{\epsilon,\delta,\rho}$ where the first three terms have been computed in Section 3.

### 5.1 Correction Terms $\rho_{ij} u^{(ij)}_{0,0,1}$

From Appendix A the term $u^{(ij)}_{0,0,1}$ is determined by the following PDE system:
\begin{equation}
\begin{align*}
\langle L_2 \rangle u^{(ij)}_{0,0,1} &= -\langle L^{(ij)}_\rho \rangle u_0, \quad x_l > B_l(t), \text{ for all } l, t < T, \\
u^{(ij)}_{0,0,1}(t, x_1, x_2, \ldots, x_n) &= 0, \quad \exists l \in \{1, \ldots, n\}, x_l = B_l(t), t \leq T, \\
u^{(ij)}_{0,0,1}(T, x_1, x_2, \ldots, x_n) &= 0, \quad x_l > B_l(t), \text{ for all } l,
\end{align*}
\end{equation}
where the operator $\langle L^{(ij)}_\rho \rangle$ is given by
\begin{equation}
\langle L^{(ij)}_\rho \rangle = \langle f_i(\cdot, z) f_j(\cdot, z) \rangle x_i x_j \frac{\partial^2}{\partial x_i \partial x_j}.
\end{equation}

The following result shows that each $u^{(ij)}_{0,0,1}$ corresponds to a single two-dimensional problem.

**Proposition 4** The correction term $\rho_{ij} u^{(ij)}_{0,0,1}$ is given by
\begin{equation}
\rho_{ij} u^{(ij)}_{0,0,1} = R^{(4)}_{ij} w^{(4)}_{ij} \prod_{k=1}^n Q_k,
\end{equation}
Proof  The proof is very similar to that of Proposition 2. With the definition (53) of 

\[ R \]

and where the function \( w^{(4)}(t, x_i, x_j) \) depends on the parameter \( z \) and is given by the following problem:

\[
\left[ \frac{\partial}{\partial t} + \frac{1}{2} \sigma^2_i(z) x_i^2 \frac{\partial^2}{\partial x_i^2} + \frac{1}{2} \sigma^2_j(z) x_j^2 \frac{\partial^2}{\partial x_j^2} + r x_i \frac{\partial}{\partial x_i} + r x_j \frac{\partial}{\partial x_j} \right] w^{(4)}_{ij} = - \left( x_i \frac{\partial Q_j}{\partial x_i} \right) \left( x_j \frac{\partial Q_i}{\partial x_j} \right)
\]

with \( \sigma_i(z) \) given in Proposition 1.

\[ w^{(4)}_{ij}(t, x_i, x_j) = 0, \quad \text{if} \quad x_i = B_i(t) \quad \text{or} \quad x_j = B_j(t), t < T, \]

\[ w^{(4)}(T, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t), \]

Proof  The proof is very similar to that of Proposition 2. With the definition (53) of \( R^{(4)}_{ij} \), we have

\[
\rho_{ij} \langle \mathcal{L}_{ij} \rangle u_0 = R^{(4)}_{ij} x_i \frac{\partial}{\partial x_i} \left( x_j \frac{\partial u_0}{\partial x_j} \right).
\]

It is therefore enough to check that

\[
\langle \mathcal{L}_2 \rangle \left( \prod_{k=1, k \neq i,j}^{n} Q_k \right) w^{(4)}_{ij} = - x_i \frac{\partial}{\partial x_i} \left( x_j \frac{\partial u_0}{\partial x_j} \right).
\]

Using the form (7) of \( \langle \mathcal{L}_2 \rangle \) and \( u_0 = \prod_{i=1}^{n} Q_i \) one can easily check that (56) is satisfied. The boundary and terminal conditions for the correction \( \rho_{ij} u_{0,0,1}^{(ij)} \) are directly inherited from the boundary and terminal conditions for the functions \( w^{(4)}_{ij} \)'s, and \( Q_i \)'s.

As for (18) we show in Appendix B that the boundary value problem with source (54) for \( w^{(4)}_{ij} \) can be transformed into boundary value problems without source leading to explicit formulas (up to Gaussian integrals).

5.2 Summary of Approximation with Name-Name Correlation

Combining the results of Propositions (1)–(4), we get that the approximation \( \tilde{u} \) in (50) is given by

\[
\tilde{u} = \prod_{i=1}^{n} Q_i + \sum_{i=1}^{n} R^{(2)}_{ij} \prod_{j=1, j \neq i}^{n} Q_j + \sum_{i=1}^{n} R^{(3)}_{ij} \prod_{j=1, j \neq i}^{n} Q_j + \sum_{i,j=1}^{n} R^{(3)}_{ij} \prod_{k=1, k \neq i,j}^{n} Q_k
+ \sum_{i=1}^{n} R^{(0)}_{ij} \prod_{j=1, j \neq i}^{n} Q_j + \sum_{i=1}^{n} R^{(1)}_{ij} \prod_{j=1, j \neq i}^{n} Q_j + \sum_{i,j=1}^{n} R^{(1)}_{ij} \prod_{k=1, k \neq i,j}^{n} Q_k
\]
\[ + \sum_{i<j}^{n} R_{ij}^{(4)} w_{ij}^{(4)} \prod_{k=1}^{n} Q_k, \tag{57} \]

where \( R_{ij}^{(4)} \) are small of order \( \rho_{ij} \) and depend on the parameter \( z \), and the functions \( w_{ij}^{(4)} \) depend on the variables \((x_i, x_j)\) and the parameter \( z \).

### 5.3 Loss Distribution (Homogeneous Portfolio)

For simplicity we only consider the homogeneous portfolio case. In addition to the homogeneity conditions (35) we also assume that \( \rho_{ij} = \rho \) for all \((i, j)\) and \( |\rho| \ll 1 \).

Using the same notation as in Section 4, the name-name correction term becomes:

\[
\sum_{i<j}^{n} \rho_{ij} u_{0,0,1}^{(ij)} = \sum_{i<j}^{n} R_{ij}^{(4)} w_{ij}^{(4)} \prod_{k=1}^{n} Q_k
\]

\[
= \frac{1}{2} n(n-1) R_{12}^{(4)} w_{12}^{(4)}(t, x, x) q^{n-2},
\]

where from (53), \( R_{12}^{(4)} = \rho \sigma^2(z) \).

In particular this implies that the approximation for the loss distribution given by (45) still holds if we redefine the quantity \( B \) in (41) as

\[
B \equiv R_{12}^{(1)} w_{12}^{(1)}(t, x, x) + R_{12}^{(3)} w_{12}^{(3)}(t, x, x) + \frac{1}{2} R_{12}^{(4)} w_{12}^{(4)}(t, x, x). \tag{58} \]

Note that for a single maturity \( T \) the correlations generated by stochastic volatility and name-name correlation are of the same form to leading order. However if one looks at the term structure of correlation across several maturities, an important aspect of CDO tranches, then the shape of the function \( w_{12}^{(4)} \) is different from the shapes of \( w_{12}^{(1)} \) and \( w_{12}^{(3)} \) and therefore the nature of the correlation plays a role.

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### References

A Formal Expansion

Following Fouque et al. (2003), we present the formal expansion used in Section 3, and we discuss its accuracy. We compute $L^{\epsilon,\delta}u^{\epsilon,\delta}$ where the operator $L^{\epsilon,\delta}$ is given by (2), and the function $u^{\epsilon,\delta}$ is first expanded in powers of $\sqrt{\delta}$ corresponding to a regular perturbation:

$$u^{\epsilon,\delta} = u_0^{\epsilon} + \sqrt{\delta} u_1^{\epsilon} + \delta u_2^{\epsilon} + \cdots$$

(59)

In order to cancel the terms of order zero in $\delta$ and the terms of order $\sqrt{\delta}$ in $L^{\epsilon,\delta}u^{\epsilon,\delta} = 0$, we get

$$\left( \frac{1}{\epsilon}\mathcal{L}_0 + \frac{1}{\sqrt{\epsilon}}\mathcal{L}_1 + \mathcal{L}_2 \right) u_0^{\epsilon} = 0$$

(60)

$$\left( \frac{1}{\epsilon}\mathcal{L}_0 + \frac{1}{\sqrt{\epsilon}}\mathcal{L}_1 + \mathcal{L}_2 \right) u_1^{\epsilon} + \mathcal{M}_1 u_0^{\epsilon} + \frac{1}{\sqrt{\epsilon}}\mathcal{M}_3 u_0^{\epsilon} = 0,$$

(61)

with zero boundary value conditions at $x_i = B_i(t)$ and a terminal condition one (resp. zero) at $t = T$ for $u_0^{\epsilon}$ (resp. $u_1^{\epsilon}$). We now expand $u_0^{\epsilon}$ in powers of $\sqrt{\epsilon}$ corresponding to a singular perturbation:

$$u^{\epsilon} = u_0 + \sqrt{\epsilon} u_{1,0} + \epsilon u_{2,0} + \epsilon\sqrt{\epsilon} u_{3,0} \cdots$$

so that (60) becomes:

$$\frac{1}{\epsilon}\mathcal{L}_0 u_0 + \frac{1}{\sqrt{\epsilon}}(\mathcal{L}_0 u_{1,0} + \mathcal{L}_1 u_0) + (\mathcal{L}_0 u_{2,0} + \mathcal{L}_1 u_{1,0} + \mathcal{L}_2 u_0) + \sqrt{\epsilon} (\mathcal{L}_0 u_{3,0} + \mathcal{L}_1 u_{2,0} + \mathcal{L}_2 u_{1,0}) + \cdots = 0$$
By choosing \( u_0 \) and \( u_{1,0} \) independent of the variable \( y \) the terms in \( 1/\epsilon \) and \( 1/\sqrt{\epsilon} \) cancel. The operator \( L_1 \) taking derivatives with respect to \( y \), the next term becomes

\[
L_0 u_{2,0} + L_2 u_0 = 0,
\]

which is a Poisson equation in \( u_{2,0} \) with respect to the variable \( y \), leading to the solvability condition

\[
\langle L_2 \rangle u_0 = 0,
\]

and the problem (6) characterizing \( u_0 \). Subsequently \( u_{2,0} \) is given by \( -L_0^{-1} (L_2 - \langle L_2 \rangle) u_0 \), and the terms of order \( \sqrt{\epsilon} \), as a Poisson equation in \( u_{3,0} \) with respect to the variable \( y \), lead to the solvability condition

\[
\langle L_2 \rangle u_{1,0} = \langle L_1 L_0^{-1} (L_2 - \langle L_2 \rangle) \rangle u_0,
\]

and the problem (9) characterizing \( u_{1,0} \).

In order to obtain \( u_{0,1} \) needed in the approximation (5), we only need the leading order term in

\[
u_1 = u_{0,1} + \sqrt{\epsilon} u_{1,1} + \cdots
\]

since \( u_1 \) is multiplied by \( \sqrt{\delta} \) in (59). By choosing \( u_{0,1} \) and \( u_{1,1} \) independent of the variable \( y \), and using the fact that \( M_3 \) takes derivatives with respect to \( y \), to leading order equation (61) becomes:

\[
L_0 u_{2,1} + L_2 u_{0,1} + M_1 u_0 = 0,
\]

which is again a Poisson equation in \( u_{2,1} \) with respect to \( y \). Its solvability condition

\[
\langle L_2 \rangle u_{0,1} = -\langle M_1 \rangle u_0
\]

leads to the problem (22) characterizing \( u_{0,1} \).

The accuracy of the the approximation (5) is the same as obtained in Fouque et al. (2006), that is \( O(\epsilon^2/3 \log |\epsilon| + \delta) \).

The computation of \( L^{\epsilon,\delta,\rho} u^{\epsilon,\delta,\rho} \), used in Section 5, proceeds along the same lines. The operator \( L^{\epsilon,\delta,\rho} \) is given by (47), and the function \( u^{\epsilon,\delta,\rho} \) is first expanded in powers of \( \rho_{ij} \) corresponding to a regular perturbation:

\[
u^{\epsilon,\delta,\rho} = u_0^{\epsilon,\delta} + \sum_{i<j} \rho_{ij} u_1^{\epsilon,\delta,ij} + \sum_{i<j} \sum_{k<l} \rho_{ij} \rho_{kl} u_2^{\epsilon,\delta,ijkl} + \cdots
\]

(62)

Canceling the terms of order zero in \( \rho_{ij} \) and the terms of order \( \rho_{ij} \) in \( L^{\epsilon,\delta,\rho} u^{\epsilon,\delta,\rho} = 0 \), we get

\[
L^{\epsilon,\delta} u_0^{\epsilon,\delta} = 0 \quad \text{(63)}
\]

\[
L^{\epsilon,\delta} u_1^{\epsilon,\delta} = -L^{(ij)} \rho^{\epsilon,\delta} u_0^{\epsilon,\delta} \quad \text{(64)}
\]

with zero boundary conditions at \( x_i = B_i(t) \) and a terminal condition one (resp. zero) at \( t = T \) for \( u_0^{\epsilon,\delta} \) (resp. \( u_1^{\epsilon,\delta} \)) where \( L^{(ij)} \rho^{(ij)} \) is given by (48). Equation (63) has been discussed above. Equation (64) has a source which is of order zero in \( \epsilon \) and in \( \delta \), so that after expanding first in \( \sqrt{\delta} \) and then in \( \sqrt{\epsilon} \), \( u_{0,0,1} \) and \( u_{1,0,1}^{(ij)} \) can be chosen independent of \( y \) to make the terms in \( 1/\epsilon \) and \( 1/\sqrt{\epsilon} \) cancel.
After dropping terms which differentiate \( u_{0,0,1}^{(ij)} \) or \( u_{1,0,1}^{(ij)} \) with respect to \( y \), to leading order equation (64) becomes

\[
\mathcal{L}_0 u_{2,0,1}^{(ij)} + \mathcal{L}_2 u_{0,0,1}^{(ij)} = -\mathcal{L}_\rho^{(ij)} u_{0,0,0}.
\]

This Poisson equation has the solvability condition

\[
\langle \mathcal{L}_2 \rangle u_{0,0,1}^{(ij)} = -\langle \mathcal{L}_\rho^{(ij)} \rangle u_{0,0,0},
\]

which is the problem (51) characterizing \( u_{0,0,1}^{(ij)} \).

\section*{B Explicit Formulas}

In order to implement the main formulas (33) and (58) for the approximation \( \hat{u} \), one needs to compute the functions \( u_i^{(l)} \) for each \( i \in \{1, 2, \cdots, n\} \), \( l \in \{0, 1, 2, 3\} \), and \( w_i^{(l)} \) for each pair \( (i, j) \in \{1, 2, \cdots, n\} \times \{1, 2, \cdots, n\} \) with \( i \neq j \), and \( l \in \{1, 3, 4\} \), defined in (16, 17, 18, 27, 28, 29, 54).

We present in this Appendix an efficient method for computing these quantities. The formulas are given below in Lemmas 2 and 3.

\textbf{Lemma 2} For each \( i \in \{1, 2, \cdots, n\} \):

a) \( w_i^{(2)} \) is given by

\[
w_i^{(2)}(t, x_i) = \hat{w}_i^{(2)}(t, x_i) - (T - t) F_i^{(2)}(t, x_i),
\]

where

\[
F_i^{(2)}(t, x_i) = x_i^2 \frac{\partial^2 Q_i}{\partial x_i^2}
\]

\[
= N' \left( d_{2(i)}^{+} \right) \left[ -\frac{d_{2(i)}^{+}}{\sigma_i^2(T-t)} - \frac{1}{\sigma_i \sqrt{T-t}} \right] - N \left( d_{2(i)}^{-} \right) p_i (p_i - 1) \left( \frac{x_i}{B_i(t)} \right)^{p_i}
\]

\[
+ N \left( d_{2(i)}^{-} \right) \left[ \frac{d_{2(i)}^{+}}{\sigma_i^2(T-t)} + \frac{2p_i - 1}{\sigma_i \sqrt{T-t}} \right] \left( \frac{x_i}{B_i(t)} \right)^{p_i},
\]

\[
\hat{w}_i^{(2)}(t, x_i) = \int_t^T g_i^{(2)}(s) h_i(s, x_i) ds,
\]

\[
g_i^{(2)}(t) = (T - t) \lim_{x_i \to B_i(t)} F_i^{(2)}(t, x_i)
\]

\[
= N'(d_i) \frac{2(p_i - 1)}{\sigma_i} \sqrt{T-t} - N(d_i) p_i (p_i - 1)(T-t),
\]

\[
h_i(s, x_i) = \frac{\ln \frac{x_i}{K_i} - \eta t}{\sigma_i \sqrt{2\pi (s-t)^3}} \exp \left\{-\frac{\left[ \ln \frac{x_i}{K_i} - \eta t - \frac{p_i \sigma_i^2}{2} (s-t) \right]^2}{2\sigma_i^2 (s-t)} \right\},
\]

\[
d_i = \frac{(r - \eta_i - \sigma_i^2/2)(T-t)}{\sigma_i \sqrt{T-t}} = -\frac{p_i \sigma_i}{2} \sqrt{T-t},
\]

\[
\end{equation*}
with $N'(\cdot)$ being the standard normal density function, and $\sigma_i \equiv \sigma_i(z)$ when no possible confusion is caused.

b) $w_i^{(3)}$ is given by
\[ w_i^{(3)}(t, x_i) = \hat{w}_i^{(3)}(t, x_i) - (T - t)F_i^{(3)}(t, x_i), \]
where
\[ F_i^{(3)}(t, x_i) = x_i \frac{\partial}{\partial x_i} \left( x_i \frac{\partial^2 Q_i}{\partial x_i^2} \right) \]
\[ = N' \left( d_2^{+}(i) \right) \left[ \frac{d_2^{+}(i)^2}{\sigma_i^2(T - t)^{3/2}} + \frac{d_2^{+}(i)}{\sigma_i^2(T - t)} \right] + N \left( d_2^{+}(i) \right) p_i^2 \left( 1 - p_i \right) \left( \frac{x_i}{B_i(t)} \right)^{p_i} \]
\[ + N' \left( d_2^{-}(i) \right) \left[ \frac{d_2^{-}(i)^2}{\sigma_i^2(T - t)^{3/2}} + \frac{d_2^{-}(i)(3p_i - 1)}{\sigma_i^2(T - t)} + \frac{p_i(3p_i - 2)}{\sigma_i \sqrt{T - t}} \right] \left( \frac{x_i}{B_i(t)} \right)^{p_i}, \]
\[ \hat{w}_i^{(3)}(t, x_i) = \int_t^T g_i^{(3)}(s) h_i(s, x_i) ds, \]
\[ g_i^{(3)}(t) \equiv (T - t) \lim_{x_i \to B_i(t)} F_i^{(3)}(t, x_i) \]
\[ = -N'(d_i) \frac{1}{\sigma_i^2} \left( \frac{2}{\sqrt{T - t}} + 4p_i \sqrt{T - t} \right) + N(d_i)p_i^2 \left( 1 - p_i \right)(T - t). \]

c) $w_i^{(0)}$ is given by
\[ w_i^{(0)}(t, x_i) = \hat{w}_i^{(0)}(t, x_i) + (T - t)F_i^{(0)}(t, x_i) - \frac{1}{2}(T - t)^2 \sigma_i F_i^{(2)}(t, x_i), \]
where
\[ F_i^{(0)}(t, x_i) \equiv \frac{\partial Q_i}{\partial \sigma_i} \]
\[ = N' \left( d_2^{+}(i) \right) \left[ - \frac{d_2^{+}(i)}{\sigma_i} - \sqrt{T - t} \right] + N' \left( d_2^{+}(i) \right) \left[ \frac{d_2^{+}(i)}{\sigma_i} + \sqrt{T - t} \right] \left( \frac{x_i}{B_i(t)} \right)^{p_i} \]
\[ + N \left( d_2^{+}(i) \right) \left[ \frac{2}{\sigma_i^2}(p_i - 1) \ln \left( \frac{x_i}{B_i(t)} \right) \right] \left( \frac{x_i}{B_i(t)} \right)^{p_i}, \]
\[ \hat{w}_i^{(0)}(t, x_i) = \int_t^T g_i^{(0)}(s) h_i(s, x_i) ds, \]
\[ g_i^{(0)}(t) \equiv -(T - t) \lim_{x_i \to B_i(t)} F_i^{(0)}(t, x_i) + \frac{1}{2}(T - t)^2 \sigma_i \lim_{x_i \to B_i(t)} F_i^{(2)}(t, x_i) \]
\[ = N'(d_i)(p_i - 1)(T - t)^{3/2} - N(d_i) \sigma_i \frac{p_i}{2} p_i(p_i - 1)(T - t)^2. \]

d) $w_i^{(1)}$ is given by
\[ w_i^{(1)}(t, x_i) = \hat{w}_i^{(1)}(t, x_i) + (T - t)F_i^{(1)}(t, x_i) - \frac{1}{2}(T - t)^2 \sigma_i F_i^{(3)}(t, x_i), \]
where

\begin{align*}
F_i^{(1)}(t, x_i) &\equiv x_i \frac{\partial}{\partial x_i} \left( \frac{\partial Q_i}{\partial \sigma_i} \right) \\
&= N' \left( d_2^+(\sigma_i^2 T - t) \right)^2 - 1 + N' \left( d_2^-(\sigma_i^2 T - t) \right)^2 + (p_i + 1) \frac{d_2^-(\sigma_i^2 T - t)}{\sigma_i} + p_i \sqrt{T - t} + \frac{2(1-p_i)}{\sigma_i^2} \ln \left( \frac{x_i}{B_i(t)} \right) \left( \frac{x_i}{B_i(t)} \right)^{p_i} + N \left( d_2^-(\sigma_i^2 T - t) \right)^2 \left( 1 + p_i \ln \left( \frac{x_i}{B_i(t)} \right) \right) \left( \frac{x_i}{B_i(t)} \right)^{p_i},
\end{align*}

\begin{align*}
\hat{w}_i^{(1)}(t, x_i) &= \int_t^T g_i^{(1)}(s) h_i(s, x_i) ds,
\end{align*}

\begin{align*}
g_i^{(1)}(t) &\equiv -(T - t) \lim_{x_i \to B_i(t)} F_i^{(1)}(t, x_i) + \frac{1}{2}(T - t)^2 \sigma_i \lim_{x_i \to B_i(t)} F_i^{(3)}(t, x_i) \\
&= N' (d_i) \frac{1}{\sigma_i^2} \left( \sqrt{T - t} - 2p_i r(T - t)^{3/2} \right) \\
&- N(d_i) \left( \frac{2}{\sigma_i} (p_i - 1)(T - t) + \frac{\sigma_i}{2} p_i^2 (p_i - 1)(T - t)^2 \right).
\end{align*}

**Proof** We use the same technique as in Fouque, Sircar and Solna (2005), but here we need to deal with the time varying hitting boundary \(B_i(t)\), whereas they considered a constant hitting boundary.

a) If we define

\begin{align*}
L_2^{(i)} &\equiv \frac{\partial}{\partial t} + \frac{1}{2} f_i^2(y, z)x_i^2 \frac{\partial^2}{\partial x_i^2} + rx_i \frac{\partial}{\partial x_i},
\end{align*}

then \(\langle L_2^{(i)} \rangle x_i^k \frac{\partial^k Q_i}{\partial x_i^k} = 0\) for \(k \geq 1\), where we used the fact that \(\langle L_2^{(i)} \rangle\) commutes with \(x_i^k \frac{\partial^k}{\partial x_i^k}\) and the fact that \(\langle L_2^{(i)} \rangle Q_i = 0\). Now we define

\begin{align*}
\hat{w}_i^{(2)}(t, x_i) &\equiv \hat{w}_i^{(2)} + (T - t)x_i^2 \frac{\partial^2 Q_i}{\partial x_i^2},
\end{align*}

which satisfies

\begin{align*}
\langle L_2^{(i)} \rangle \hat{w}_i^{(2)}(t, x_i) &= 0, \quad x_i > B_i(t), t < T, \\
\hat{w}_i^{(2)}(t, B_i(t)) &= (T - t) \lim_{x_i \to B_i(t)} x_i^2 \frac{\partial^2 Q_i}{\partial x_i^2} \equiv g_i^{(2)}(t), \quad t \leq T, \\
\hat{w}_i^{(2)}(T, x_i) &= 0, \quad x_i > B_i(t).
\end{align*}

Change of variables: define

\begin{align*}
\xi_i &\equiv \frac{1}{\sigma_i} \ln \frac{x_i}{B_i(t)}, \\
\bar{\mu}_i &\equiv \frac{r - \eta_i - \sigma_i^2/2}{\sigma_i} = -\frac{p_i \sigma_i}{2}, \\
\hat{w}_i^{(2)}(t, \xi_i) &\equiv \hat{w}_i^{(2)}(t, x_i).
\end{align*}
Then \( \bar{w}_i^{(2)} (t, \xi_i) \) satisfies
\[
\frac{\partial \bar{w}_i^{(2)}}{\partial t} + \frac{1}{2} \frac{\partial^2 \bar{w}_i^{(2)}}{\partial \xi_i^2} + \bar{\mu}_i \frac{\partial \bar{w}_i^{(2)}}{\partial \xi_i} = 0, \quad \xi_i > 0, t < T,
\]
\[
\bar{w}_i^{(2)} (t, 0) = g_i^{(2)} (t), \quad t \leq T,
\]
\[
\bar{w}_i^{(2)} (T, \xi_i) = 0, \quad \xi_i > 0.
\]

It follows that, see, for example, Karatzas and Shreve (1991), \( \bar{w}_i^{(2)} \) admits the probabilistic representation:
\[
\bar{w}_i^{(2)} (t, \xi_i) = \mathbb{E}^Q \left[ g_i^{(2)} (\tau^*) \mathbf{1}_{\{ \tau^* \leq T \}} \bigg| \xi_t^{(i)} = \xi_i \right],
\]
where \( \xi^{(i)} \) is a Brownian motion with drift \( \bar{\mu}_i \) under probability measure \( Q \), and \( \tau^* \) is the first time that \( \xi^{(i)} \) hits 0. By plugging in the distribution of \( \tau^* \), which is well known and can be found, for example, in Borodin and Salminen (2002), we obtain
\[
\bar{w}_i^{(2)} (t, \xi_i) = \int_t^T g_i^{(2)} (s) \frac{\xi_i}{\sqrt{2\pi(s-t)^3}} \exp \left\{ -\frac{\left[ \xi_i + \bar{\mu}_i (s-t) \right]^2}{2(s-t)} \right\} ds
\]
\[
= \int_t^T g_i^{(2)} (s) h_i (s) ds.
\]
So in summary,
\[
w_i^{(2)} = \bar{w}_i^{(2)} - (T-t)x_i^2 \frac{\partial^2 Q_i}{\partial x_i^2} = \bar{w}_i^{(2)} - (T-t)F_i^{(2)} (t, x_i).
\]

b) The same as that for part a).

c) Note that
\[
\langle L_2^{(i)} \rangle \frac{\partial Q_i}{\partial \sigma_i} = -\sigma_i x_i^2 \frac{\partial^2 Q_i}{\partial x_i^2},
\]
which can be obtained by taking derivative with respect to \( \sigma_i \) on equation \( \langle L_2^{(i)} \rangle Q_i = 0 \). Now define
\[
\hat{w}_i^{(0)} = w_i^{(0)} - (T-t) \frac{\partial Q_i}{\partial \sigma_i} + \frac{1}{2} (T-t)^2 \sigma_i x_i^2 \frac{\partial^2 Q_i}{\partial x_i^2},
\]
then \( \hat{w}_i^{(0)} (t, x_i) \) satisfies
\[
\langle L_2^{(i)} \rangle \hat{w}_i^{(0)} (t, x_i) = 0, \quad x_i > B_i (t), t < T,
\]
\[
\hat{w}_i^{(0)} (t, B_i (t)) = g_i^{(0)} (t), \quad t \leq T,
\]
\[
\hat{w}_i^{(0)} (T, x_i) = 0, \quad x_i > B_i (t).
\]

The rest of the proof is as in part a).
Lemma 3 For each pair \((i,j) \in \{1, 2, \ldots, n\} \times \{1, 2, \ldots, n\}\) with \(i \neq j\):

a) \(w^{(3)}_{ij}\) is given by

\[
w^{(3)}_{ij}(t, x_i, x_j) = w^{(3)}_{ij}(t, x_i, x_j) - (T - t)F^{(3)}_{ij}(t, x_i, x_j),
\]

where

\[
F^{(3)}_{ij}(t, x_i, x_j) = \left(x_i \frac{\partial Q_i}{\partial x_i} \right) \left(x_j \frac{\partial^2 Q_j}{\partial x_j^2}\right)
= F^{(2)}_j(t, x_j) \left[N' \left(\frac{d^+_2(i)}{\sigma_j \sqrt{T} - t}\right) + N' \left(\frac{d^-_2(i)}{\sigma_j \sqrt{T} - t}\right) + N \left(\frac{d^-_2(i)}{B_i(t)}\right) - N \left(\frac{d^-_2(i)}{B_i(t)}\right) \right],
\]

\[
\hat{w}^{(3)}_{ij}(t, x_i, x_j) = \int_t^T \int_0^\infty \hat{G}_{ij}^{(j)}(s, \xi) \psi_j(s, \xi, x_j) h_{ij}(s, x_i, x_j) d\xi ds
+ \int_t^T \int_0^\infty \hat{G}_{ij}^{(i)}(s, \xi) \psi_i(s, \xi, x_i) h_{ij}(s, x_j, x_i) d\xi ds,
\]

\[
\psi_j(s, \xi, x_j) = \frac{2}{\sqrt{2\pi(s-t)}} \sinh \left(\frac{\xi \ln \frac{x_i}{B_i(t)}}{\sigma_j(s-t)}\right) \exp \left\{-\frac{\xi^2}{2(s-t)} - \frac{\sigma_j \xi}{2}\right\},
\]

\[
h_{ij}(s, x_i, x_j) = h_i(s, x_i) \exp \left\{-\frac{\left[\ln \frac{x_i}{B_i(t)} - \eta_j t - \frac{p_j \sigma_j^2}{2}(s-t)\right]^2}{2\sigma_j^2(s-t)}\right\},
\]

\[
\hat{G}_{ij}^{(j)}(t, \xi) = (T-t) F^{(3)}_{ij}(t, B_i(t), B_j(t)) e^{\sigma_j \xi}
= \left[N'(d_j) \frac{2}{\sigma_j} \sqrt{T} - t - N(d_j) p_j(T-t)\right] \times \left\{ \frac{N' \left(d^+_2(j)\right)}{\sigma_j^2(T-t)} \right\} - N \left(d^-_2(j)\right) p_j(T-t) e^{\sigma_j \xi}
+ \left[N' \left(d^-_2(j)\right) \frac{2p_j - 1}{\sigma_j \sqrt{T} - t}\right] e^{\sigma_j \xi},
\]

\[
\hat{G}_{ij}^{(i)}(t, \xi) = (T-t) F^{(3)}_{ij}(t, B_i(t)) e^{\sigma_i \xi, B_j(t)}
= \left[N'(d_j) \frac{2}{\sigma_j} \sqrt{T} - t - N(d_j) p_j(T-t)\right] \times \left(\frac{p_j - 1}{\sigma_j} \sqrt{T} - t - N(d_j) p_j(T-t)\right) e^{\sigma_i \xi},
\]

All the calculations of the formulas within this lemma are straightforward. The proof is complete.
where
\[ w_{ij}^{(1)} = \pm \xi - \frac{p_i \sigma_j}{\sqrt{2(T-t)}} \]

**b) \( w_{ij}^{(1)} \)** is given by

\[ w_{ij}^{(1)}(t, x_i, x_j) = \hat{w}_{ij}^{(1)}(t, x_i, x_j) + (T-t) F_{ij}^{(1)}(t, x_i, x_j) - \frac{1}{2} (T-t)^2 \sigma_j F_{ij}^{(3)}(t, x_i, x_j), \]

where

\[
F_{ij}^{(1)}(t, x_i, x_j) = \left( x_i \left( \frac{\partial Q_i}{\partial x_i} \right) - x_j \left( \frac{\partial Q_j}{\partial x_j} \right) \right) \left( \frac{1}{\sigma_i \sqrt{T-t}} \right) + N' \left( d_{2(i)}^- \right) \frac{e^{p_i \sigma_j \xi}}{\sigma_i \sqrt{T-t}} - N \left( d_{2(i)}^- \right) p_i e^{p_i \sigma_j \xi}, \]

\[
\hat{w}_{ij}^{(1)}(t, x_i, x_j) = \int_0^T \int_0^T \tilde{H}_{ij}^{(1)}(s, x_i, x_j) h_{ij}(s, x_i, x_j) ds \]

\[
\tilde{H}_{ij}^{(1)}(t, x_i, x_j) = \left( \frac{2}{\sigma_i \sqrt{T-t}} \right) + N' \left( d_{2(i)}^- \right) \left( \frac{1}{2} \right)^{p_i} + N' \left( d_{2(i)}^- \right) \left( \frac{1}{2} \right)^{p_j} + \left( 2 \xi + \frac{p_i \sigma_j}{2} (T-t) \right) e^{p_i \sigma_j \xi}, \]

\[
\tilde{H}_{ij}^{(3)}(t, x_i, x_j) = \left( \frac{2}{\sigma_i \sqrt{T-t}} \right) + N' \left( d_{2(i)}^- \right) \left( \frac{1}{2} \right)^{p_i} + N' \left( d_{2(i)}^- \right) \left( \frac{1}{2} \right)^{p_j} + \left( 2 \xi + \frac{p_i \sigma_j}{2} (T-t) \right) e^{p_i \sigma_j \xi}. \]

**c) \( w_{ij}^{(4)} \)** is given by

\[ w_{ij}^{(4)}(t, x_i, x_j) = \hat{w}_{ij}^{(4)}(t, x_i, x_j) - (T-t) F_{ij}^{(4)}(t, x_i, x_j), \]

where

\[
F_{ij}^{(4)}(t, x_i, x_j) = - \left( x_i \left( \frac{\partial Q_i}{\partial x_i} \right) - x_j \left( \frac{\partial Q_j}{\partial x_j} \right) \right) \left( \frac{1}{\sigma_i \sqrt{T-t}} \right) + N' \left( d_{2(i)}^- \right) \frac{e^{p_i \sigma_j \xi}}{\sigma_i \sqrt{T-t}} - N \left( d_{2(i)}^- \right) p_i e^{p_i \sigma_j \xi}. \]
= - \left[ N^i d_2^j + N^j d_2^i \right] \frac{1}{\sigma_i \sqrt{T - t}} + N^i d_{2(i)} \left( \frac{x_i}{B_i(t)} \right)^{p_i}

\bar{w}_{ij}^{(4)}(t, x_i, x_j) = \int_t^T \int_0^\infty \bar{K}_{ij}^{(j)}(s, \xi) \psi_j(s, \xi, x_j) h_{ij}(s, x_i, x_j) d\xi ds

+ \int_t^T \int_0^\infty \bar{K}_{ij}^{(i)}(s, \xi) \psi_i(s, \xi, x_i) h_{ij}(s, x_i, x_j) d\xi ds,

\bar{K}_{ij}^{(j)}(t, \xi) \equiv (T - t) F_{ij}^{(4)} \left( t, B_i(t), B_j(t) e^{\sigma_j} \xi \right),

\bar{K}_{ij}^{(i)}(t, \xi) \equiv (T - t) F_{ij}^{(4)} \left( t, B_i(t) e^{\sigma_i} \xi, B_j(t) \right).

**Proof**

a) If we define

\[ \mathcal{L}_2^{(ij)} = \frac{\partial}{\partial t} + \frac{1}{2} f_i^2(y, z) x_i^2 \frac{\partial^2}{\partial x_i^2} + \frac{1}{2} f_j^2(y, z) x_j^2 \frac{\partial^2}{\partial x_j^2} + r x_i \frac{\partial}{\partial x_i} + r x_j \frac{\partial}{\partial x_j}, \]

then \( (\mathcal{L}_2^{(ij)} x_i^k \frac{\partial Q_j}{\partial x_i}) = 0 \) for \( k \geq 1 \). Next we define

\[ \tilde{w}_{ij}^{(3)} \equiv w_{ij}^{(3)} + (T - t) \left( x_i \frac{\partial Q_i}{\partial x_i} \right) \left( x_j^2 \frac{\partial^2 Q_j}{\partial x_j^2} \right), \]

which satisfies

\[ (\mathcal{L}_2^{(ij)} \tilde{w}_{ij}^{(3)}(t, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t), t < T, \]

\[ \tilde{w}_{ij}^{(3)}(t, B_i(t), x_j) = (T - t) F_{ij}^{(3)}(t, B_i(t), x_j) \equiv G_{ij}^{(j)}(t, x_j), \quad x_j > B_j(t), t \leq T, \]

\[ \tilde{w}_{ij}^{(3)}(t, x_i, B_j(t)) = (T - t) F_{ij}^{(3)}(t, x_i, B_j(t)) \equiv G_{ij}^{(i)}(t, x_i), \quad x_i > B_i(t), t \leq T, \]

\[ \tilde{w}_{ij}^{(3)}(T, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t). \]

**Change of variables**: define

\[ \xi_i \equiv \frac{1}{\sigma_i} \ln \frac{x_i}{B_i(t)}, \quad \xi_j \equiv \frac{1}{\sigma_j} \ln \frac{x_j}{B_j(t)}, \]

\[ \bar{\mu}_i \equiv \frac{r - \eta_i - \sigma_i^2/2}{\sigma_i} = \frac{p_i \sigma_i}{2}, \quad \bar{\mu}_j \equiv \frac{r - \eta_j - \sigma_j^2/2}{\sigma_j} = -\frac{p_j \sigma_j}{2}, \]

and also

\[ \tilde{w}_{ij}^{(3)}(t, \xi_i, \xi_j) \equiv \tilde{w}_{ij}^{(3)}(t, x_i, x_j), \]

\[ \tilde{G}_{ij}^{(j)}(t, \xi_j) \equiv G_{ij}^{(j)}(t, x_j) = G_{ij}^{(j)} \left( t, B_j(t) e^{\sigma_j \xi_j} \right), \]

\[ \tilde{G}_{ij}^{(i)}(t, \xi_i) \equiv G_{ij}^{(i)}(t, x_i) = G_{ij}^{(i)} \left( t, B_i(t) e^{\sigma_i \xi_i} \right). \]
Then we have
\[ \frac{\partial \hat{w}_{ij}^{(3)}}{\partial t} + \frac{1}{2} \frac{\partial^2 \hat{w}_{ij}^{(3)}}{\partial \xi_i^2} + \frac{1}{2} \frac{\partial^2 \hat{w}_{ij}^{(3)}}{\partial \xi_j^2} + \mu_i \frac{\partial \hat{w}_{ij}^{(3)}}{\partial \xi_i} + \mu_j \frac{\partial \hat{w}_{ij}^{(3)}}{\partial \xi_j} = 0, \]
\[ \xi_i > 0, \xi_j > 0, t < T, \]
\[ \hat{w}_{ij}^{(3)}(t, 0, \xi_j) = \overline{G}^{(j)}_{ij}(t, \xi_j), \]
\[ \hat{w}_{ij}^{(3)}(t, \xi_i, 0) = \overline{G}^{(i)}_{ij}(t, \xi_i), \]
\[ \hat{w}_{ij}^{(3)}(T, \xi_i, \xi_j) = 0, \]
\[ \xi_i > 0, \xi_j > 0, t < T. \]

The function \( \hat{w}_{ij}^{(3)} \) admits the probabilistic representation:
\[
\hat{w}_{ij}^{(3)}(t, \xi_i, \xi_j) = \mathbb{E}^Q \left\{ \overline{G}^{(j)}_{ij} \left( \tau, \xi^{(j)}_\tau \right) 1_{\{ \tau = \tau_i \}} 1_{\{ \tau \leq T \}} + \overline{G}^{(i)}_{ij} \left( \tau, \xi^{(i)}_\tau \right) 1_{\{ \tau = \tau_j \}} 1_{\{ \tau \leq T \}} \bigg| \xi_t^{(i)} = \xi_i, \xi_t^{(j)} = \xi_j \right\},
\]
where \( \xi^{(i)} \) and \( \xi^{(j)} \) are independent Brownian motions with drifts \( \bar{\mu}_i \) and \( \bar{\mu}_j \), respectively, under probability measure \( Q \). \( \tau, (\tau_j) \) is the first time that \( \xi^{(i)} (\xi^{(j)}) \) hits 0, and \( \tau = \min\{ \tau_i, \tau_j \} \). From Borodin and Salminen (2002), we have
\[
\hat{h}_{ij}(s, \xi; \xi_i, \xi_j) = \mathbb{Q} \left\{ \tau \in ds, \tau = \tau_i, \xi^{(j)}_\tau \in d\xi \big| \xi_t^{(i)} = \xi_i, \xi_t^{(j)} = \xi_j \right\} = \frac{2}{\sqrt{2\pi(s-t)}} \sinh \left( \frac{\xi \xi_i}{s-t} \right) \exp \left\{ \frac{\xi \mu_j - \xi^2}{2(s-t)} \right\} \exp \left\{ -\frac{[\xi_j + \mu_j (s-t)]^2}{2(s-t)} \right\} \times \frac{\xi_i}{\sqrt{2\pi(s-t)^3}} \exp \left\{ -\frac{[\xi_i + \mu_i (s-t)]^2}{2(s-t)} \right\} d\xi ds.
\]
Therefore,
\[
\hat{w}_{ij}^{(3)}(t, \xi_i, \xi_j) = \int_t^T \int_0^\infty \overline{G}^{(j)}_{ij}(s, \xi) \hat{h}_{ij}(s, \xi; \xi_i, \xi_j) d\xi ds
\]
\[+ \int_t^T \int_0^\infty \overline{G}^{(i)}_{ij}(s, \xi) \hat{h}_{ij}(s, \xi; \xi_i, \xi_i) d\xi ds.
\]
Now change \((\xi_i, \xi_j)\) back to \((x_i, x_j)\) to obtain the desired result.

b) Define
\[
\hat{w}_{ij}^{(1)} \equiv w_{ij}^{(1)} - (T-t) \left( x_i \frac{\partial Q_{ij}}{\partial x_i} \right) \left( x_j \frac{\partial Q_{ij}}{\partial x_j} \right) + \frac{1}{2} (T-t)^2 \sigma_j \left( x_i \frac{\partial Q_{ij}}{\partial x_i} \right) \left( x_j \frac{\partial^2 Q_{ij}}{\partial x_j^2} \right).
\]
Then \( \hat{w}_{ij}^{(1)} \) satisfies
\[
(L_2^{(ij)}) \hat{w}_{ij}^{(1)}(t, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t), t < T,
\]
\[
\hat{w}_{ij}^{(1)}(t, B_i(t), x_j) = -(T-t)F_{ij}^{(1)}(t, B_i(t), x_j) + \frac{1}{2} (T-t)^2 \sigma_j F_{ij}^{(3)}(t, B_i(t), x_j), \quad x_j > B_j(t), t \leq T,
\]
\[
\hat{w}_{ij}^{(1)}(t, x_i, B_j(t)) = -(T-t)F_{ij}^{(1)}(t, x_i, B_j(t)) + \frac{1}{2} (T-t)^2 \sigma_j F_{ij}^{(3)}(t, x_i, B_j(t)), \quad x_i > B_i(t), t \leq T,
\]
\[
\hat{w}_{ij}^{(1)}(T, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t).
\]
The rest of the proof is similar to that of part a).

c) Define

\[ \hat{w}^{(4)}_{ij} \equiv w^{(4)}_{ij} - (T - t) \left( x_i \frac{\partial Q_i}{\partial x_i} \right) \left( x_j \frac{\partial Q_j}{\partial x_j} \right). \]

Then \( \hat{w}^{(4)}_{ij} \) satisfies

\[
\langle L^{(ij)}_2 \rangle \hat{w}^{(4)}_{ij} (t, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t), t < T,
\]

\[
\hat{w}^{(1)}_{ij} (t, B_i(t), x_j) = -(T - t) F^{(4)}_{ij} (t, B_i(t), x_j), \quad x_j > B_j(t), t \leq T,
\]

\[
\hat{w}^{(4)}_{ij} (t, x_i, B_j(t)) = -(T - t) F^{(4)}_{ij} (t, x_i, B_j(t)), \quad x_i > B_i(t), t \leq T,
\]

\[
\hat{w}^{(4)}_{ij} (T, x_i, x_j) = 0, \quad x_i > B_i(t), x_j > B_j(t).
\]

The rest of the proof is similar to that of part a). The proof is complete.